

**SIGNALS FOR TESTING NONLINEAR SYSTEMS**

by

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### Summary

The purpose of this paper is to describe some work on the synthesis of test signals for the measurement of kernels in nonlinear systems.

Given an input,  $x(t)$ , of a stationary, lumped parameter nonlinear system, the output,  $y(t)$ , can be represented as a functional of the past history of the input ( $y(t) = F(x(t-\tau))$ ;  $\tau < t$ ). This functional can always be expanded into a sum of functionals (1,2):

$$y(t) = h_0 + \int_0^{\infty} h_1(\tau)x(t-\tau)d\tau + \int_0^{\infty} \int_0^{\infty} h_2(\tau_1, \tau_2)x(t-\tau_1)x(t-\tau_2)d\tau_1d\tau_2 \\ + \int_0^{\infty} \int_0^{\infty} \int_0^{\infty} h_3(\tau_1, \tau_2, \tau_3)x(t-\tau_1)x(t-\tau_2)x(t-\tau_3)d\tau_1d\tau_2d\tau_3 + \dots \quad (1)$$

where  $h_1$  are kernels characteristic of the system in question and, without loss of generality, may be assumed to be symmetrical.

In many practical applications, it is of particular interest to know the linear kernel  $h_1$  whose spectrum is the transfer function of the first approximation of the system. In view of the noise present in physical systems, the question arises as to whether an input can be designed which permits the measurement of  $h_1$  without restriction on the amplitude of  $x(t)$ .

To this end, a number of periodic signals has been designed which allows the exact measurement of  $h_1$ , by means of crosscorrelation measurements between input and output, in nonlinear systems which can be satisfactorily described by a functional representation of the form

$$y(t) = h_0 + \int_0^{\infty} h_1(\tau)x(t-\tau)d\tau + \int_0^{\infty} \int_0^{\infty} h_2(\tau_1, \tau_2)x(t-\tau_1)x(t-\tau_2)d\tau_1d\tau_2 \quad (2)$$

One family of periodic signals is defined by the following properties:

- (a) At any instant of time, the signal may assume only one of three possible values, +1, 0, or -1.
- (b) The signal is discontinuous and may change value at event points having uniform spacing  $\Delta t$ .
- (c) The signal is periodic with period  $T = N\Delta t$  where  $N = 3^n - 1$ ,  $n = \text{integer}$ .
- (d) The  $j$ -th bit is given by the recursion formula

$$C_j = a_1 C_{j-1} + a_2 C_{j-2} + \dots + a_n C_{j-n} \quad ; \quad a_1 = \text{integer} \quad (3)$$

where the right side is reduced modulo-3 so that  $C_j$  assumes the values, +1, 0, or -1. Given  $n$ , signals with period  $N\Delta t$  exist only for certain values of the coefficients  $a_1, a_2, \dots, a_n$ .

Similar families of signals can be designed with  $N = p^n - 1$ ; where  $p$  is a prime integer  $> 2$  and equal to the number of possible levels of the signal.

(e) If the  $n$ -th order correlation function is defined as

$$R_n(\tau_1, \dots, \tau_n) = \int_{-T/2}^{T/2} x(t) x(t + \tau_n) dt \quad (4)$$

then the preceding families of signals have a first order correlation function as shown in Fig. 1 and a second order correlation function which is zero everywhere.

For signals of this family, it is easily established that the crosscorrelation of  $y(t)$  of Eq. (2) with  $x(t)$ , over an integer number of periods, yields

$$\int_0^{kT} x(t - \tau_1) y(t) dt \approx h_1(\tau_1) ; \quad k = \text{integer} \quad (5)$$

provided that  $h_1$  is negligibly small for  $\tau_1 > T/2$  (3).

The family of signals discussed above can be used for reactor transfer function measurements with better accuracy than is attainable with the binary signals presented in (3).

Efforts are currently underway to design signals whose higher order correlation functions closely approximate the corresponding correlation functions of Gaussian white noise (1). The objectives of these efforts are the measurement of  $h_1$  in the presence of kernels of order three and higher as well as the measurement of the higher order kernels themselves.

#### References

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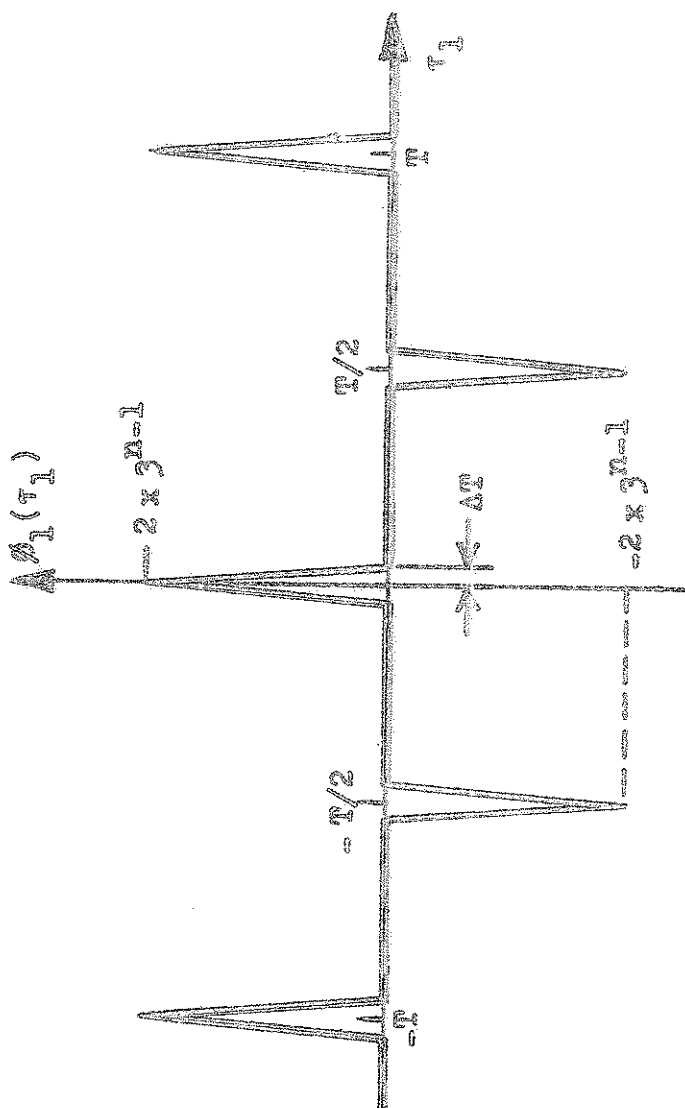


Figure 1. First order correlation function of periodic ternary sequence.